TRANSPORTATION AND HUMAN FACTORS: AEROSPACE, AVIATION, MARITIME, RAILROAD, AND ROADS

Designing Interaction and Interfaces for Automated Vehicles

User-Centred Ecological Design and Testing

Edited by Neville A. Stanton, Kirsten M.A. Revell and Patrick Langdon



Designing Interaction and Interfaces for Automated Vehicles

Transportation and Human Factors

Aerospace, Aviation. Maritime, Railroad, and Roads

Series Editor: Professor Neville A. Stanton University of Southampton, UK

PUBLISHED TITLES

Automobile Automation

Distributed Cognition on the Road Victoria A. Banks and Neville A. Stanton

Eco-Driving

From Strategies to Interfaces
Rich C. McIlroy and Neville A. Stanton

Driver Reactions to Automated Vehicles

A Practical Guide for Design and Evaluation Alexander Eriksson and Neville A. Stanton

Systems Thinking in Practice

Applications of the Event Analysis of Systemic Teamwork Method Paul Salmon, Neville A. Stanton, and Guy Walker

Individual Latent Error Detection (I-LED)

Making Systems Safer

Justin R.E. Saward and Neville A. Stanton

Driver Distraction

A Sociotechnical Systems Approach

Kate J. Parnell, Neville A. Stanton, and Katherine L. Plant

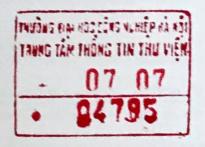
Designing Interaction and Interfaces for Automated Vehicles

User-Centred Ecological Design and Testing
Neville Stanton, Kirsten M.A. Revell, and Patrick Langdon

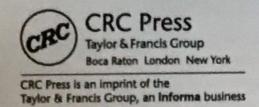
For more information about this series, please visit https://www.erepress.com/ Transportation-Human-Factors/book-series/CRCTRNHTATACATR

Designing Interaction and Interfaces for Automated Vehicles

User-Centred Ecological Design and Testing



Neville A. Stanton, Kirsten M. A. Revell, and Patrick Langdon



First edition published 2021 by CRC Press 6000 Broken Sound Parkway NW, Suite 300, Boca Raton, FL 33487-2742

and by CRC Press 2 Park Square, Milton Park, Abingdon, Oxon, OX14 4RN

© 2021 Taylor & Francis Group, LLC

Reasonable efforts have been made to publish reliable data and information, but the author and publisher cannot assume responsibility for the validity of all materials or the consequences of their use. The authors and publishers have attempted to trace the copyright holders of all material reproduced in this publication and apologize to copyright holders if permission to publish in this form has not been obtained. If any copyright material has not been acknowledged please write and let us know so we may rectify in any future reprint.

Except as permitted under U.S. Copyright Law, no part of this book may be reprinted, reproduced, transmitted, or utilized in any form by any electronic, mechanical, or other means, now known or hereafter invented, including photocopying, microfilming, and recording, or in any information storage or retrieval system, without written permission from the publishers.

For permission to photocopy or use material electronically from this work, access www.copyright. com or contact the Copyright Clearance Center, Inc. (CCC), 222 Rosewood Drive, Danvers, MA 01923, 978-750-8400. For works that are not available on CCC please contact mpkbookspermissions@tandf.co.uk

Trademark Notice: Product or corporate names may be trademarks or registered trademarks and are used only for identification and explanation without intent to infringe.

Library of Congress Cataloging-in-Publication Data

Names: Stanton, Neville A. (Neville Anthony), 120 editoral Revell, Kirsten M. A., editor. | Langdon, Patrick, 1961-editor.

Title: Designing interaction and interfaces for automated vehicles: user-centred ecological design and testing / edited by Neville A Stanton, Kirsten M. A. Revell, and Pat Langdon.

Description: First edition. | Boca Raton, FL: CRC Press/Taylor & Francis Group, LLC, 2021. |

Series: Transportation human factors : aerospace, aviation, maritime, rail, and road | Includes bibliographical references and index. |

Summary: "Driving Automation and Autonomy is already upon us and the problems that were predicted twenty years ago are beginning to appear. These problems include shortfalls in expected benefits, equipment unreliability, driver skill fade, and error-inducing equipment designs. This book investigates the difficult problem of how to interface drivers with automated vehicles by offering an inclusive, human-centered design process that focuses on human variability and capability in interaction with interfaces. This book is for designers of systems interfaces, interactions, UX, Human Factors and Ergonomics researchers, and practitioners involved with systems engineering, and automotive academics"— Provided by publisher.

Identifiers: LCCN 2020047985 (print) | LCCN 2020047986 (ebook) | ISBN 9780367466640 (hardback) | ISBN 9781003050841 (ebook)

Subjects: LCSH: Automated vehicles. | Human-machine systems. | Automobile driving—Human factors.

Classification: LCC TL152.8 .D475 2021 (print) | LCC TL152.8 (ebook) | DDC 629.20285/5437—dc23 LC record available at https://lccn.loc.gov/2020047985

LC ebook record available at https://lccn.loc.gov/2020047986

ISBN: 9780367466640 (hbk) ISBN: 9781003050841 (ebk)

Typeset in Times by CodeMantra



Contents

Acknowledge Editors Contributors	ements
PART I	Modelling
Chapter 1	UCEID – The Best of Both Worlds: Combining Ecological Interface Design with User-Centred Design in a Novel Human Factors Method Applied to Automated Driving
	Kirsten M. A. Revell, Patrick Langdon, Michael Bradley, Ioannis Politis, James W.H. Brown, Simon Thompson, Lee Skrypchuk, Alexandros Mouzakitis, and Neville A. Stanton
Chapter 2	Using UCEID to Include the Excluded: An Autonomous Vehicle HMI Inclusive Design Case Study
	Michael Bradley, Nermin Caber, Patrick Langdon, P. John Clarkson, Simon Thompson, Lee Skrypchuk, Alexandros Mouzakitis, Ioannis Politis, Joy Richardson, Jisun Kim, James W.H. Brown, Kirsten M. A. Revell, and Neville A. Stanton
Chapter 3	Designing Autonomy in Cars: A Survey and Two Focus Groups on Driving Habits of an Inclusive User Group, and Group Attitudes towards Autonomous Cars
	Ioannis Politis, Patrick Langdon, Michael Bradley, Lee Skrypchuk, Alexandros Mouzakitis, P. John Clarkson, and Neville A. Stanton
PART II	Lo-Fi and Hi-Fi Simulators
Chapter 4	An Evaluation of Inclusive Dialogue-Based Interfaces for the Takeover of Control in Autonomous Cars
	Ioannis Politis, Patrick Langdon, Damilola Adebayo, Michael Bradley, P. John Clarkson, Lee Skrypchuk, Alexandros Mouzakitis, Alexander Eriksson, James W.H. Brown, Kirsten M. A. Revell, and Neville A. Stanton

Chapter 5	The Design of Takeover Requests in Autonomous Vehicles: Low-Fidelity Studies	69
	Patrick Langdon, Nermin Caber, Michael Bradley, Theocharis Amanatidis, James W.H. Brown, Simon Thompson, Joy Richardson, Lee Skrypchuk, Kirsten M. A. Revell, Jediah R. Clark, Joannis Politis, P. John Clarkson, and Neville A. Stanton	
Chapter 6	How Was It for You? Comparing How Different Levels of Multimodal Situation Awareness Feedback Are Experienced by Human Agents during Transfer of Control of the Driving Task in a Semi-Autonomous Vehicle	101
	Kirsten M. A. Revell, James W.H. Brown, Joy Richardson, Jisun Kim, and Neville A. Stanton	
Chapter 7	Human Driver Post-Takeover Driving Performance in Highly Automated Vehicles	115
	James W.H. Brown, Kirsten M. A. Revell, Joy Richardson, Ioannis Politis, Patrick Langdon, Michael Bradley, Simon Thompson, Lee Skrypchuk, and Neville A. Stanton	
Chapter 8	Validating Operator Event Sequence Diagrams: The Case of Automated Vehicle-to-Human Driver Takeovers	137
	Neville A. Stanton, James W.H. Brown, Kirsten M. A. Revell, Patrick Langdon, Michael Bradley, Ioannis Politis, Lee Skrypchuk, Simon Thompson, and Alexandros Mouzakitis	
PART III	Benchmarking	
Chapter 9	Breaking the Cycle of Frustration: Applying Neisser's Perceptual Cycle Model to Drivers of Semi-Autonomous Vehicles	161
	Kirsten M. A. Revell, Joy Richardson, Patrick Langdon, Michael Bradley, Ioannis Politis, Simon Thompson, Lee Skrypchuk, Jim O'Donoghue, Alexandros Mouzakitis, and Neville A. Stanton	
Chapter 10	Semi-Automated Driving Has Higher Workload and Is Less Acceptable to Drivers than Manual Vehicles: An On-Road Comparison of Three Contemporary SAE Level 2 Vehicles	187
	Jisun Kim, Kirsten M. A. Revell, Patrick Langdon, Michael Bradley, Ioannis Politis, Simon Thompson, Lee Skrypchuk, Jim O'Donoghue, Joy Richardson, and Neville A. Stanton	

Chapter 11	The Iconography of Vehicle Automation – A Focus Group Study211
	Joy Richardson, Kirsten M. A. Revell, Jisun Kim, and Neville A. Stanton
PART IV	HMI Simulator
Chapter 12	Customisation of Takeover Guidance in Semi-Autonomous Vehicles
	James W. H. Brown, Kirsten M. A. Revell, Joy Richardson, Jediah R. Clark, Nermin Caber, Theocharis Amanatidis, Patrick Langdon, Michael Bradley, Simon Thompson, Lee Skrypchuk, and Neville A. Stanton
Chapter 13	Effects of Interface Customisation on Drivers' Takeover Experience in Highly Automated Driving
	Jisun Kim, Kirsten M. A. Revell, James W. H. Brown, Joy Richardson, Jediah R. Clark, Nermin Caber, Michael Bradley, Patrick Langdon, Simon Thompson, Lee Skrypchuk, and Neville A. Stanton
Chapter 14	Accommodating Drivers' Preferences Using a Customised Takeover Interface
	Nermin Caber, Patrick Langdon, Michael Bradley, Theocharis Amanatidis, James W.H. Brown, Simon Thompson, Joy Richardson, Lee Skrypchuk, Kirsten M. A. Revell, Jediah R. Clark, Ioannis Politis, P. John Clarkson, and Neville A. Stanton
Chapter 15	Modelling Automation–Human Driver Interactions in Vehicle Takeovers Using OESDs
	Neville A. Stanton, James W. H. Brown, Kirsten M. A. Revell, Jediah R. Clark, Joy Richardson, Patrick Langdon, Michael Bradley, Nermin Caber, Lee Skrypchuk, and Simon Thompson
Chapter 16	Feedback in Highly Automated Vehicles: What Do Drivers Rely on in Simulated and Real-World Environments?
	Joy Richardson, James W.H. Brown, Jediah R. Clark, Nermin Caber, Michael Bradley, Patrick Langdon, Kirsten M. A. Revell, and Neville A. Stanton

PART V	On-Road and Design Guidelines
Chapter 17	Can Allowing Interface Customisation Increase Driver Confidence and Safety Levels in Automated Vehicle TORs?345
	James W.H. Brown, Kirsten M. A. Revell, Joy Richardson, Jisun Kim, Nermin Caber, Patrick Langdon, Michael Bradley, Simon Thompson, Lee Skrypchuk, and Neville A. Stanton
Chapter 18	Effects of Customisable HMI on Subjective Evaluation of Takeover Experience on the Road
	Jisun Kim, Kirsten M. A. Revell, James W.H. Brown, Joy Richardson, Nermin Caber, Michael Bradley, Patrick Langdon, Simon Thompson, Lee Skrypchuk, and Neville A. Stanton
Chapter 19	Accommodating Drivers' Preferences Using a Customised Takeover Interface on UK Motorways
	Nermin Caber, Patrick Langdon, Michael Bradley, James W.H. Brown, Simon Thompson, Joy Richardson, Jisun Kim, Lee Skrypchuk, Kirsten M. A. Revell, P. John Clarkson, and Neville A. Stanton
Chapter 20	Validating OESDs in an On-Road Study of Semi-Automated Vehicle-to-Human Driver Takeovers
	Neville A. Stanton, James W. H. Brown, Kirsten M. A. Revell, Jisun Kim, Joy Richardson, Patrick Langdon, Michael Bradley, Nermin Caber, Lee Skrypchuk, and Simon Thompson
Chapter 21	Design Constraints and Guidelines for the Automation–Human Interface
	Neville A. Stanton, Kirsten M. A. Revell, James W. H. Brown, Jisun Kim, Joy Richardson, Nermin Caber, Michael Bradley, and Patrick Langdon
Author Ind Subject Ind	ex

Preface

This project has developed a new approach for the design of handovers between the vehicle automation and the human driver. The approach brings together a range of methods from user-centred design, inclusive design, and ecological interface design. This approach has been used to design customisable human—machine interfaces for automation—driver handovers and has been formally tested in driving simulators and in a Jaguar I-PACE on a British motorway. Validation studies were undertaken, and design guidelines were produced. This project discovered that there were links between customisation and user performance. In particular, the handover times were quicker (on average, but with a greater range) with customised settings than the defaults. Drivers much preferred the customised settings to the defaults, and there was no adverse effect on post-handover driving performance (in terms of lane and speed stability). This is one of the first studies of its type in the UK and Europe, with a genuine automated vehicle driving (rather than being driven by a surrogate driver from the passenger seat or rear of the vehicle).

New insights into the customisation of handovers between vehicle automation and the human driver have been generated. A new method for the design of driver-vehicle interfaces has been developed, called 'user-centred ecological interface design' (UCEID). Modelling of the handovers has been validated by comparing the predictions made in operator event sequence diagrams with videos of the behaviour of human drivers, both in simulators and on the road. An on-road comparison study (Tesla, Mercedes, I-PACE) has revealed the differences between the strategies of manufacturers and shown the way this affects the human driver. The research is being published in a series of peer-reviewed journal articles and this book.

This project has uncovered a number of important factors associated with the development of automated vehicles. Numerous key design requirements that Jaguar Land Rover (JLR) can take forward into their development process have been established. These include operator event sequence diagrams that describe the process of handover. This project has also developed intuitive human—machine interface proposals and evaluations that could form part of future vehicle interfaces. There are also novel findings around the topic of customisation that will potentially increase customer satisfaction with handovers in certain automated vehicle scenarios. This project has also created specific intellectual property for JLR that could be used in future vehicles related to the handover from automation to manual driving. Additionally, a process that goes from the basic scientific foundation through to the finalised, and evaluated, concept following a series of design iterations, called the 'UCEID process', has been defined and shared with JLR for use in future vehicle programme design. Guidelines for the design of handovers between the vehicle automation and the human driver have also been presented in the final chapter of this book.

Prof Neville A. Stanton, PhD, DSc University of Southampton